

1) We have

$$x_{k+1}^1 = -a_1 x_k^1 + x_k^2 + b_1 u_k + h_1 e_k \quad (1)$$

$$x_{k+1}^2 = -a_2 x_k^1 + b_2 u_k + h_2 e_k \quad (2)$$

$$y_k = x_k^1 + e_k \quad (3)$$

From (1)

$$x_{k+2}^1 = -a_1 x_{k+1}^1 + x_{k+1}^2 + b_1 u_{k+1} + h_1 e_{k+1}$$

Use x_{k+1}^2 from (2) and we get

$$x_{k+2}^1 = -a_1 x_{k+1}^1 + (-a_2 x_k^1 + b_2 u_k + h_2 e_k) + b_1 u_{k+1} + h_1 e_{k+1} \quad (4)$$

Use y_k from 3, i.e. substitute $x_k^1 = y_k - e_k$ in (4)

$$y_{k+2} - e_{k+2} = -a_1(y_{k+1} - e_{k+1}) - a_2(y_k - e_k) + b_2 u_k + h_2 e_k + b_1 u_{k+1} + h_1 e_{k+1}$$

- \Downarrow

$$y_{k+2} = [-y_k - y_{k+1} \ u_k \ u_{k+1}] \begin{bmatrix} a_2 \\ a_1 \\ b_2 \\ b_1 \end{bmatrix} + e_{k+2} + a_1 e_{k+1} + h_1 e_{k+1} + a_2 e_k + h_2 e_k$$

ARX model when

$$\underline{h_1 = -a_1} \quad \text{and} \quad \underline{h_2 = -a_2}$$

Then

$$y_k = \phi_k^T \theta + e_k$$

where

$$\underline{\phi_k^T = [-y_{k-2} - y_{k-1} \ u_{k-2} \ u_{k-1}]}, \quad \underline{\theta = \begin{bmatrix} a_2 \\ a_1 \\ b_2 \\ b_1 \end{bmatrix}}$$

Notice that We have an 2
ARMAX model $\Rightarrow e_{k+2} + (a_1 + k_1)e_{k+1} + (a_2 + k_2)e_k$

$$y_{k+2} + a_1 y_{k+1} + a_2 y_k = b_1 u_k + \phi_1 u_{k+1} +$$

$$\cancel{e_{k+2} + k_1 e_{k+1} + k_2 e_k}$$

Using $q^{-1}y_k = y_{k-1}$ and $q y_{k-1} = y_k$

$$y_k + a_1 y_{k-1} + a_2 y_{k-2} = b_1 u_{k-1} + b_2 u_{k-2}$$

$$+ \cancel{e_k + k_1 e_{k-1} + k_2 e_{k-2}}^{k_2 + a_2}$$

and

$$(1 + a_1 q^{-1} + a_2 q^{-2}) y_k = \underbrace{(b_1 q^{-1} + \phi_2 q^{-2})}_{B(q)} u_k + \underbrace{(1 + k_1 q^{-1} + k_2 q^{-2})}_{C(q)} e_k$$

This is an ARMAX model

$$A(q) y_k = B(q) u_k + C(q) e_k //$$

where

$$C(q) = 1 + (k_1 + a_1)q^{-1} + (k_2 + a_2)q^{-2} //$$

$$B(q) = b_1 q^{-1} + \phi_2 q^{-2}, \quad A(q) = 1 + a_1 q^{-1} + a_2 q^{-2} //$$

1e) $y_n \forall n=1, \dots, t$

$$\hat{\theta}_t = \frac{1}{t} \sum_{k=1}^t y_k \quad (1)$$

$$\hat{\theta}_t = \frac{1}{t} \left(\sum_{k=1}^{t-1} y_k + y_t \right) \quad (2)$$

Divide up sum

From (1)

$$\hat{\theta}_{t-1} = \frac{1}{t-1} \sum_{k=1}^{t-1} y_k \Rightarrow \sum_{k=1}^{t-1} y_k = (t-1) \hat{\theta}_{t-1}$$

Put into (1)

$$\hat{\theta}_t = \frac{1}{t} \left((t-1) \hat{\theta}_{t-1} + y_t \right) =$$

$$= \frac{1}{t} \left(t \hat{\theta}_{t-1} + y_t - \hat{\theta}_{t-1} \right)$$

$$\boxed{\hat{\theta}_t = \hat{\theta}_{t-1} + \frac{1}{t} (y_t - \hat{\theta}_{t-1})}$$