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## On Ordinary Least Squares (OLS) regression

## 1 Ordinary Least Squares (OLS) regression

Consider a linear regression model of the form

$$Y = XB + E,\tag{1}$$

where  $Y \in \Re^{N \times m}$  is a matrix with measured observations,  $X \in \Re^{N \times r}$  is a matrix with known measured quantities. X often consists of regression variables or regressors. the elements in Y is often called regressed variables.  $E \in \Re^{N \times m}$  is a matrix with unknown variables or equation errors, noise or errors due to modeling errors.

Consider the performance index

$$V(B) = ||E||_F^2 = \operatorname{tr}(E^T E)$$
  
=  $\operatorname{tr}((Y - XB)^T (Y - XB))$   
=  $\operatorname{tr}((Y^T Y - 2Y^T XB + B^T X^T XB)$  (2)

This is a convex optimization problem and the solution is found from

$$\frac{\partial V(B)}{\partial B} = -2X^T Y + 2X^T X B = 0, \qquad (3)$$

witch gives

$$B_{OLS} = (X^T X)^{-1} X^T Y.$$
 (4)

The predicted output matrix  $\bar{Y}$  is then given by

$$\bar{Y} = XB_{OLS} = X(X^T X)^{-1} X^T Y,$$
(5)

and the prediction error

$$\varepsilon = Y - \bar{Y}.\tag{6}$$

## 2 Examples

**Example 2.1** Given pressure and temperature measurements of saturated steam in a tank  $(p_k, T_k) \forall k = 1, 2, ..., N$ . A relationship between temperature and pressure may be expressed with the Clausius Clapeyron equation

$$p = c_1 e^{c_2 T_k}. (7)$$

A non-linear equation may often simply be expressed as an linear equation using the natural logarithm operator  $ln(\dot{)}$ , *i.e.*,

$$ln(p) = ln(c_1) + ln(e^{c_2 T_k}) = ln(c_1) + c_2 T.$$
(8)

We have here used that  $lne^{c} = c$  and ln(AB) = ln(A) + ln(B).

## References

Syllabus: Prediction Error Method (PEM)